

# Interference Queuing Networks on Grids

Abishek Sankararaman, François Baccelli and Sergey Foss

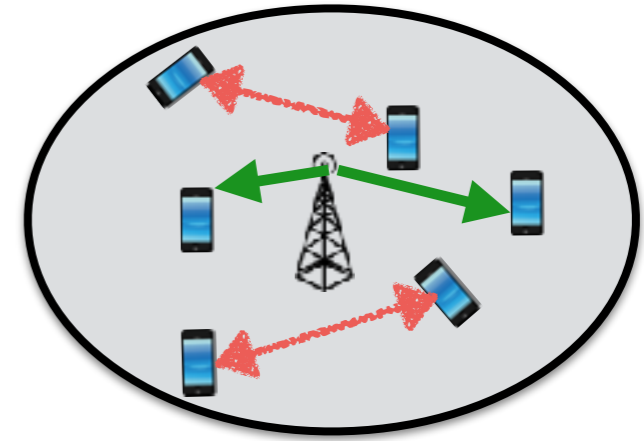
# Ad-Hoc Wireless Networks

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Networks without a centralized infrastructure

Examples -

1) Overlaid Device-to-Device (D2D) Networks

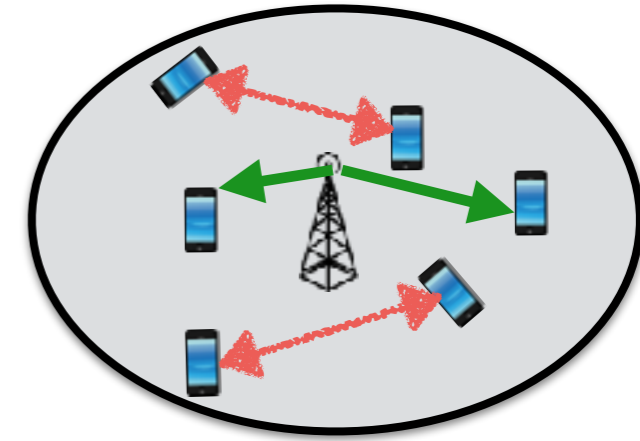


# Ad-Hoc Wireless Networks

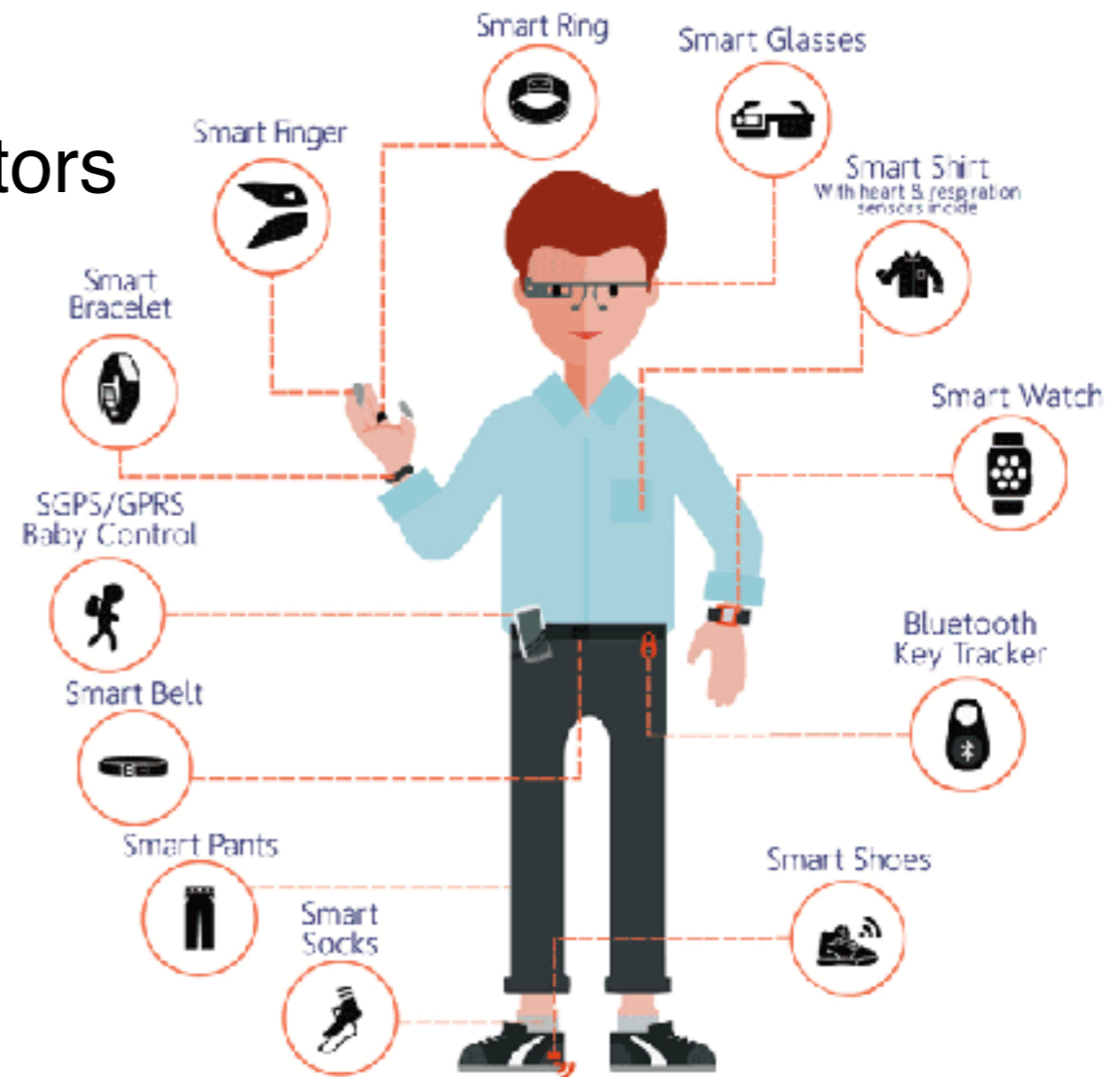
Networks without a centralized infrastructure

Examples -

1) Overlaid Device-to-Device (D2D) Networks



2) Internet of Things - Sensors and monitors



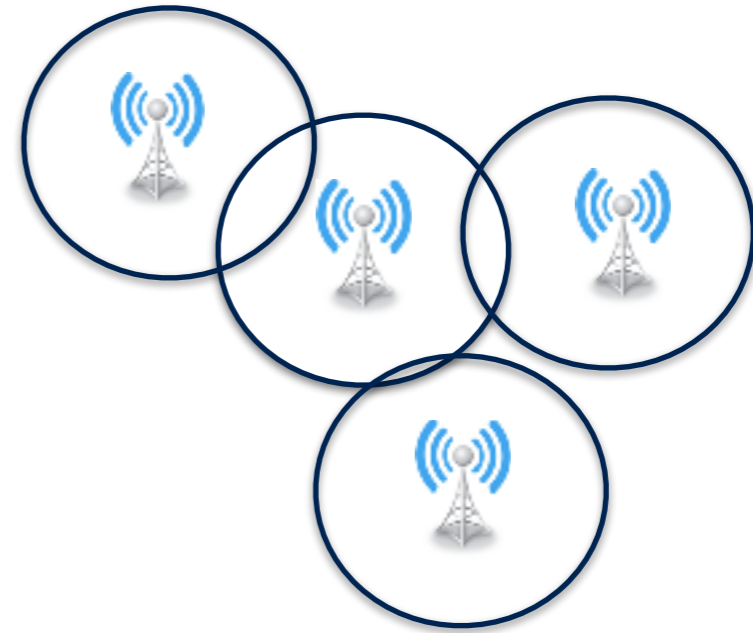
*Wireless devices everywhere !*

# Spatio-Temporal Dynamics

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Wireless Spectrum is a space-time shared resource

Spatial Component - Interference

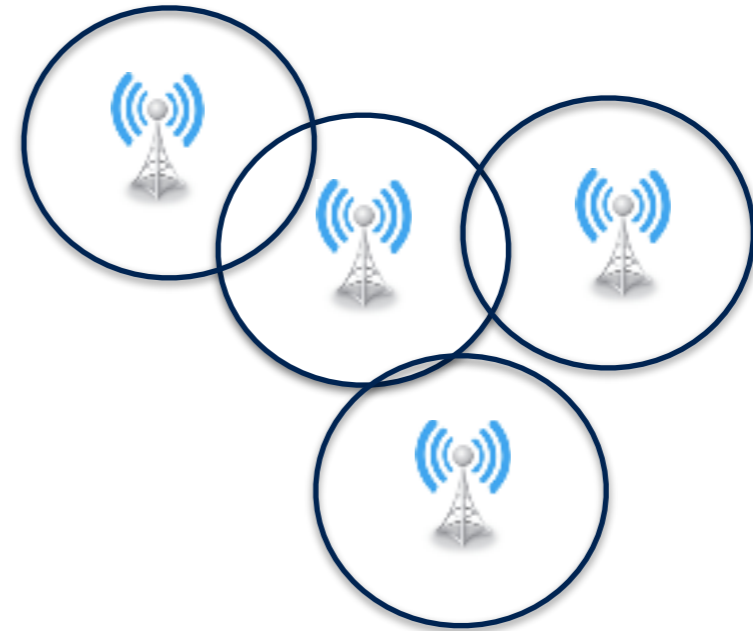


# Spatio-Temporal Dynamics

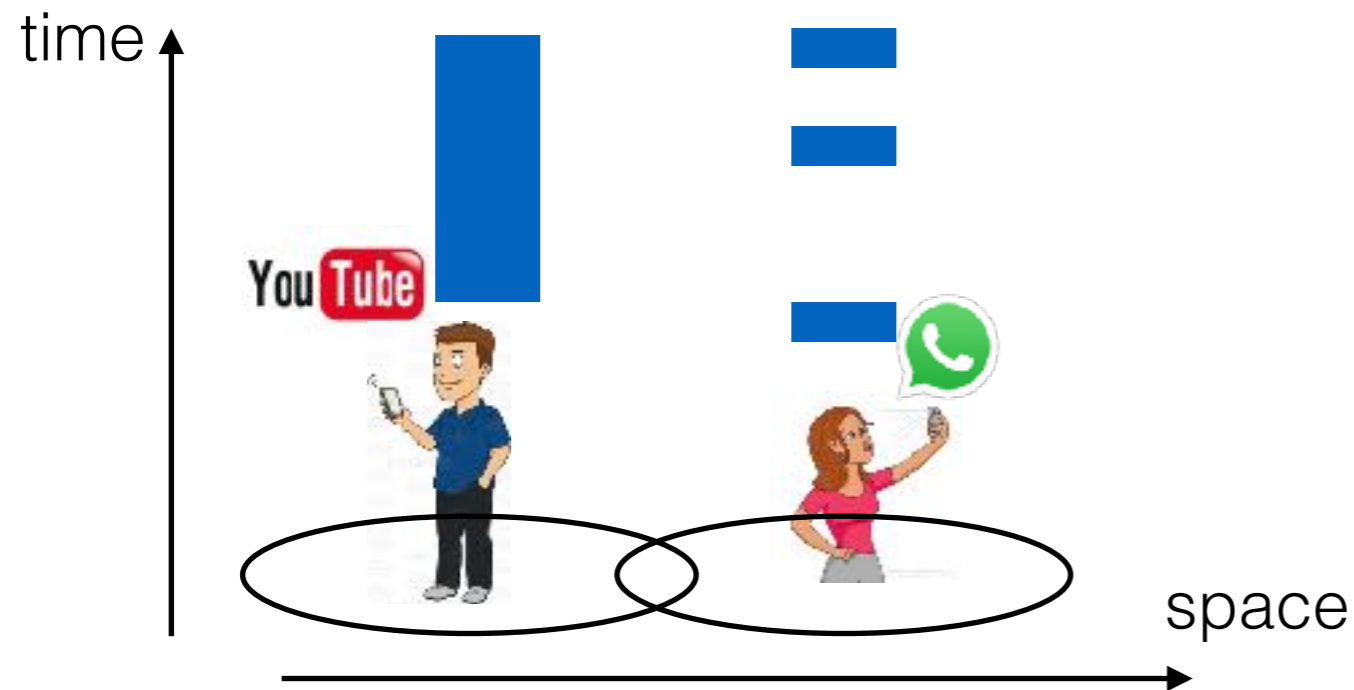
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Wireless Spectrum is a space-time shared resource

Spatial Component - Interference



Temporal Component - Traffic Patterns



Understanding the interplay of space-time interactions is crucial for design

# Prior Work

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Ad-hoc networks have been studied for a long time !

However, little is understood on the spatio-temporal interactions

## 1. Static spatial setting

[Gupta et al. 00][Baccelli et al. 03][Andrews et al. 07][De-Veciana et al. 08]

[Haenggi et al. 09]

(Does not precisely capture interactions through traffic arrivals)

## 2. Flow-based queuing models

[Bonald et al. 06][Srikant et al. 07][Shah et al, 09][Shakkottai et al. 07]

[De-Veciana et al. 08]

(Does not capture precisely, the information-theoretic interactions)

***We provide a framework to capture interactions in space and time***

# Schematic - Spatial Birth-Death Process

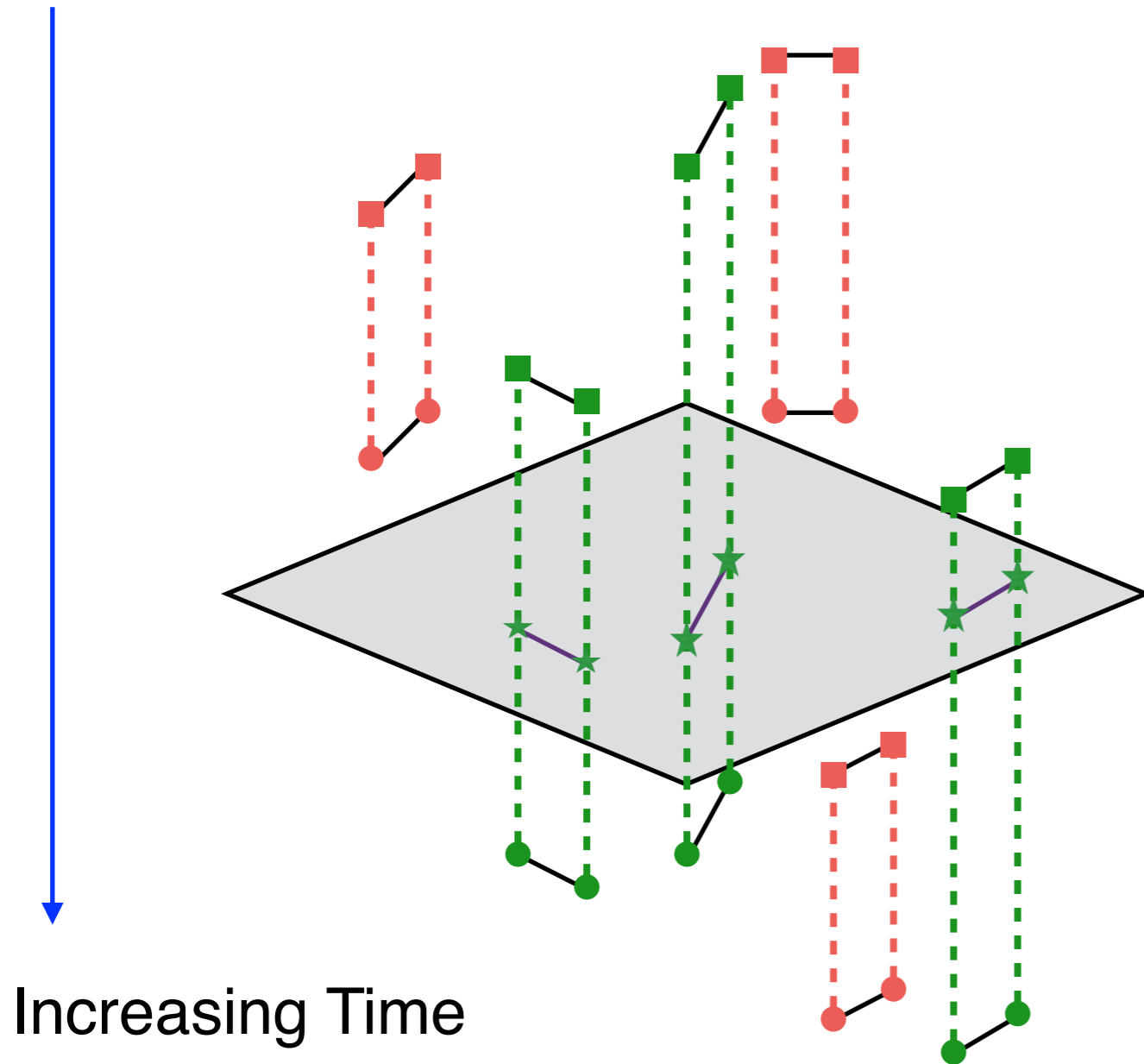
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Protocol - *A link transmits whenever they have a file by treating interference as noise*

# Schematic - Spatial Birth-Death Process

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When does this protocol “work” ?

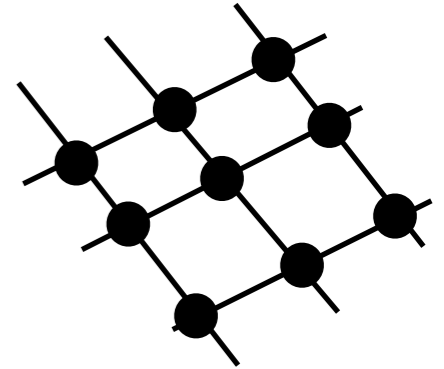


# Wireless Dynamics on Grids

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Protocol - *A link transmits whenever they have a file by treating interference as noise*

Discrete Space -  $d$  dimensional grid



# Wireless Dynamics on Grids

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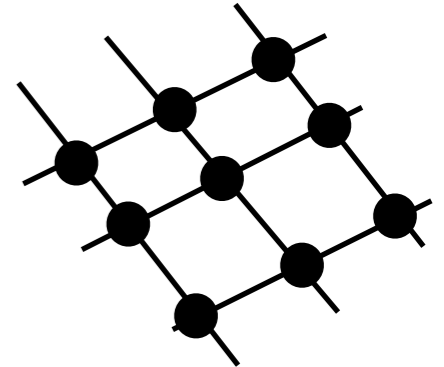
Protocol - *A link transmits whenever they have a file by treating interference as noise*

Discrete Space -  $d$  dimensional grid

Each wireless link (Tx-Rx pair) is abstracted as a point

Links (points) 'arrive' uniformly in space and transmit

Links exit after completion of a file transfer



# Wireless Dynamics on Grids

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Protocol - *A link transmits whenever they have a file by treating interference as noise*

Discrete Space - d dimensional grid

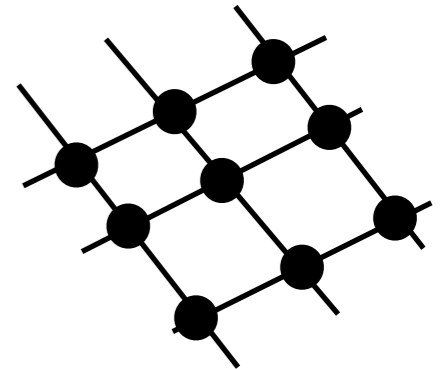
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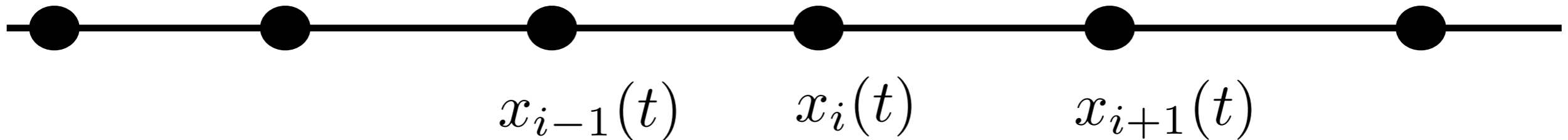
Instantaneous rate of transfer - Linearization of Shannon capacity formula

Interference as Noise



# A warm up to the Model

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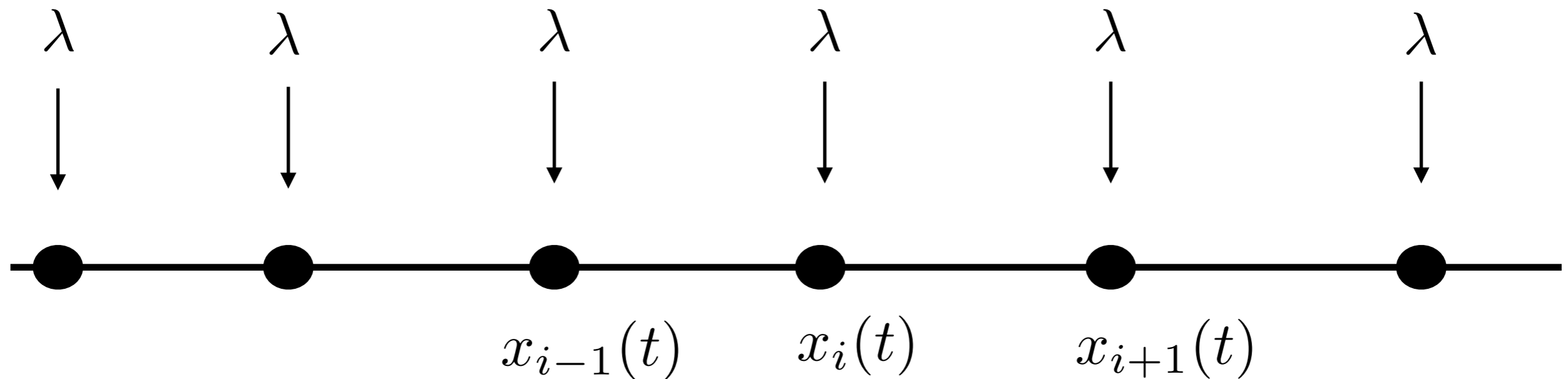


$x_i(t) \in \mathbb{N}$  Number of links in cell  $i \in \mathbb{Z}$  at time  $t \geq 0$

$\{x_i(t)\}_{i \in \mathbb{Z}}$  Queue lengths at time  $t \geq 0$

# A warm up to the Model

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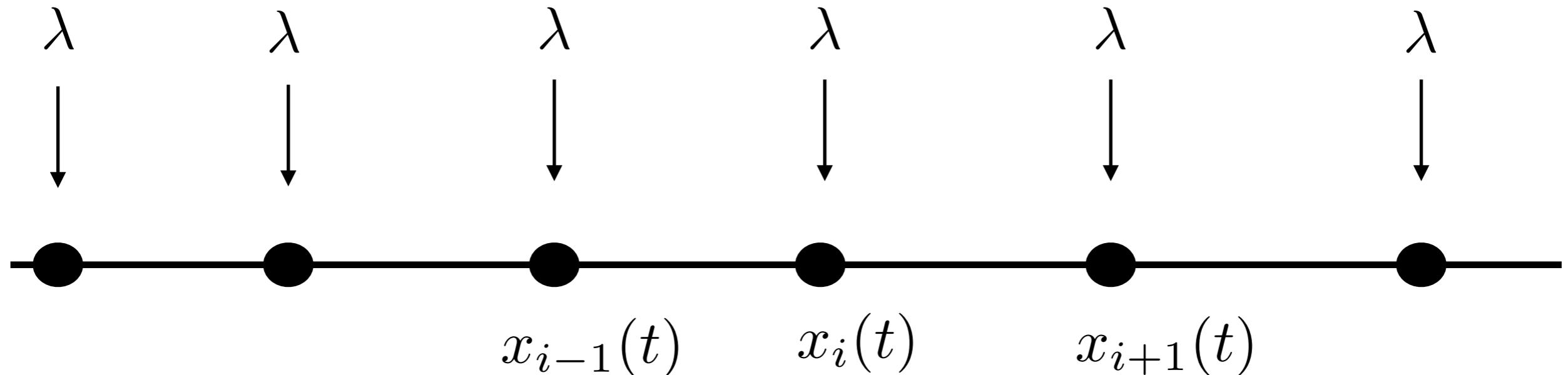


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Independent Poisson Arrivals

# A warm up to the Model



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Independent Poisson Arrivals

Rate of departure from queue  $i \in \mathbb{Z}$  at time  $t$   $\frac{x_i(t)}{x_{i-1}(t) + x_i(t) + x_{i+1}(t)}$

*If 'neighboring' queues are large, instantaneous departure rate is small.*

# Rate of Departure - SIR

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$\{x_i(t)\}_{i \in \mathbb{Z}^d} \in \mathbb{N}^{\mathbb{Z}^d}$  Queue Lengths

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Interference Sequence  $\{a_i\}_{i \in \mathbb{Z}^d}$



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Interference Sequence  $\{a_i\}_{i \in \mathbb{Z}^d}$

$$a_i \geq 0 \quad \forall i \in \mathbb{Z}^d$$

$$a_0 = 1$$

$$a_i = a_{-i} \quad \forall i \in \mathbb{Z}^d$$

$$L = \sup\{\|i\|_\infty : a_i > 0\} < \infty$$

*Positivity*

*Symmetry*

*Finite Support*

Interference at queue  $i$  -  $\sum_{j \in \mathbb{Z}^d} a_j x_{i-j}(t)$

SIR at a customer in queue  $i$  at time  $t$   $\frac{1}{\sum_{j \in \mathbb{Z}^d} a_j x_{i-j}(t)}$

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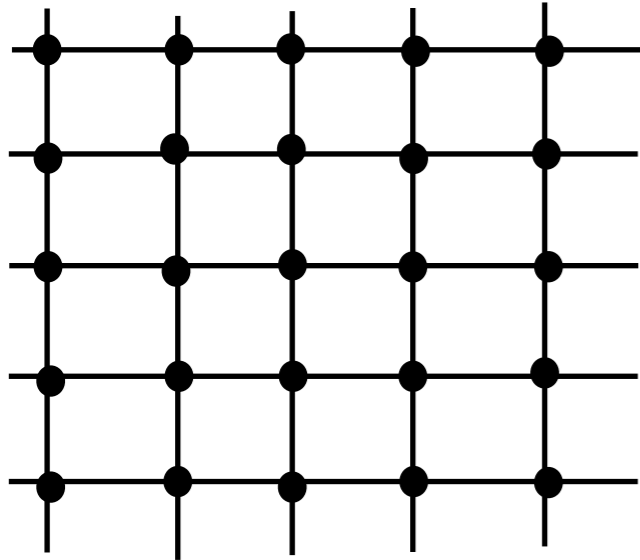
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SIR at a customer in queue  $i$  at time  $t$   $\frac{1}{\sum_{j \in \mathbb{Z}^d} a_j x_{i-j}(t)}$

Rate of departure from any queue  $i$  at time  $t$   $\frac{x_i(t)}{\sum_{j \in \mathbb{Z}^d} a_j x_{i-j}(t)}$

*Translation Invariant in Space*

# Interference Queueing Dynamics



$\{x_i(t)\}_{i \in \mathbb{Z}^d} \in \mathbb{N}^{\mathbb{Z}^d}$  Queue lengths at time  $t \geq 0$

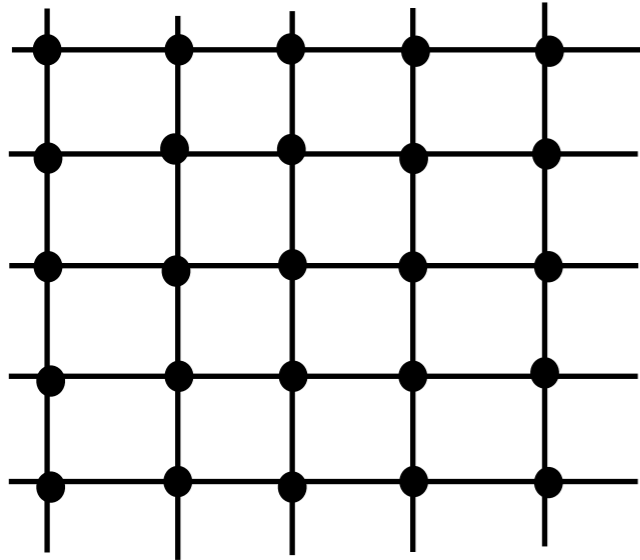
Independent rate  $\lambda$  Poisson arrivals

Rate of departure from queue  $i \in \mathbb{Z}$  at time  $t$   $\frac{x_i(t)}{\sum_{j \in \mathbb{Z}^d} a_j x_{i-j}(t)}$

*If 'neighboring' queues are large, instantaneous departure rate is small.*

In the toy example,  $a_i = 1$  if  $|i| \leq 1$  and  $a_i = 0$  otherwise

# Interference Queueing Dynamics



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Independent rate  $\lambda$  Poisson arrivals

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*If 'neighboring' queues are large, instantaneous departure rate is small.*

## Questions -

- 1) For what  $\lambda$  and  $\{a_i\}_{i \in \mathbb{Z}^d}$ , is the process  $\{x_i(t)\}_{i \in \mathbb{Z}^d}$  'stable' ?
- 2) Characterize the steady state ??

# Connection with Related Models

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Few Papers discuss Infinite Queuing Networks

- 1) Kelbert-Kontsevich-Rybko: *On Jackson Networks on Denumerable Graphs*, 1988.
- 2) Foss, Chernova: *On stability of polling models with infinite number of queues*, 1996.
- 3) Borovkov-Korshunov-Schassberger: *Ergodicity of a polling network with an infinite number of stations*, 1999.
- 4) Baccelli-Foss: *Poisson Hail on a Hot Ground*, 2011.

Similarities to *Interacting Particle System* (Liggett, 1985).

*However, each particle (queue) has a countable number of states.*

# Main Results

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## 1. Stability

If  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1$ , then system is stable

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If  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1$ , then system is stable

## 2. Moments

Let  $\{y_i\}_{i \in \mathbb{Z}^d}$  be the minimal stationary solution to the dynamics

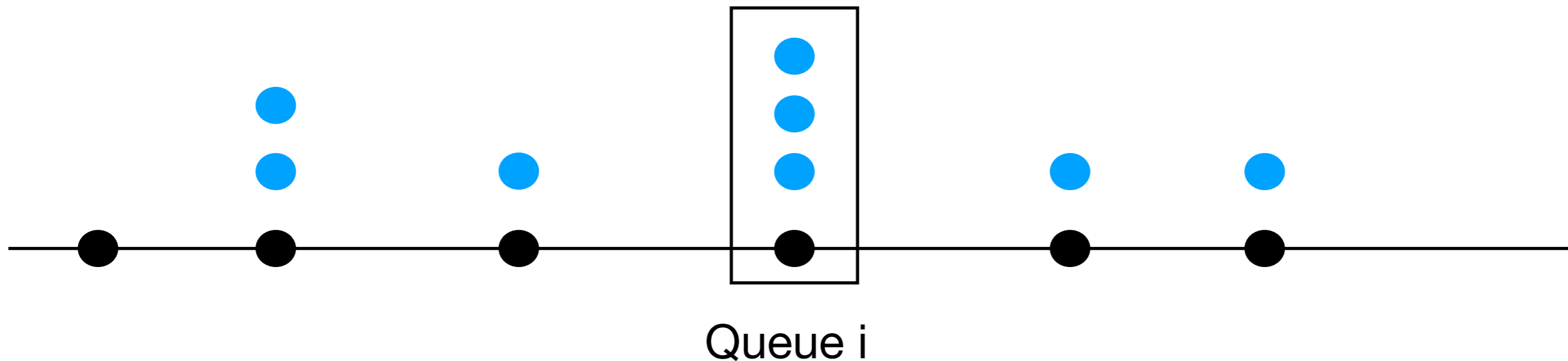
If  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1$ , then  $\mathbb{E}[y_0] = \frac{\lambda}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j}$

If  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < \frac{2}{3}$  then  $\mathbb{E}[y_0^2] < \infty$

*[Shneer and Stolyar'18] established this for the entire stability range*

*In upcoming work with Sayan Banerjee, we show exponential moments exist in the entire range*

# Intuition



Consider any local maximum queue  $i$ , i.e.  $x_i(t) = \max\{x_{i-j}(t) : a_j > 0\}$

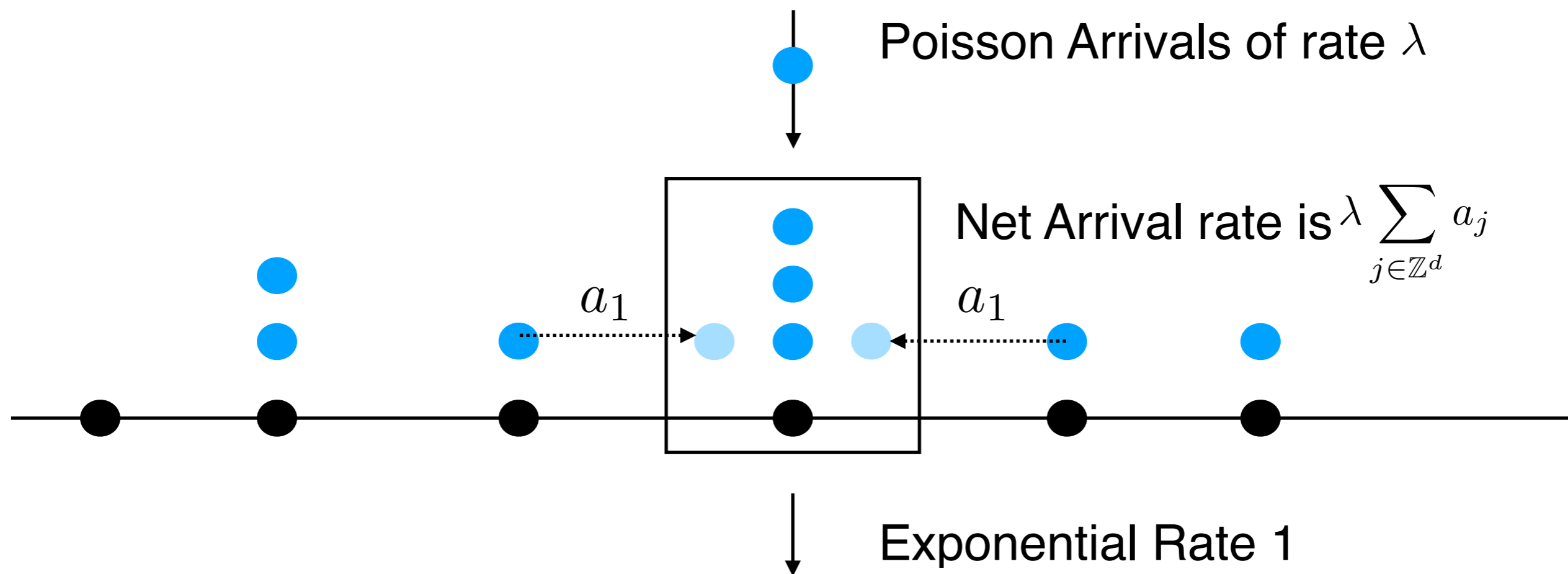
Its instantaneous departure rate is  $\frac{x_i(t)}{\sum_{j \in \mathbb{Z}^d} a_j x_{i-j}(t)} \geq \frac{1}{\sum_{j \in \mathbb{Z}^d} a_j}$

The arrival rate at every queue is  $\lambda$

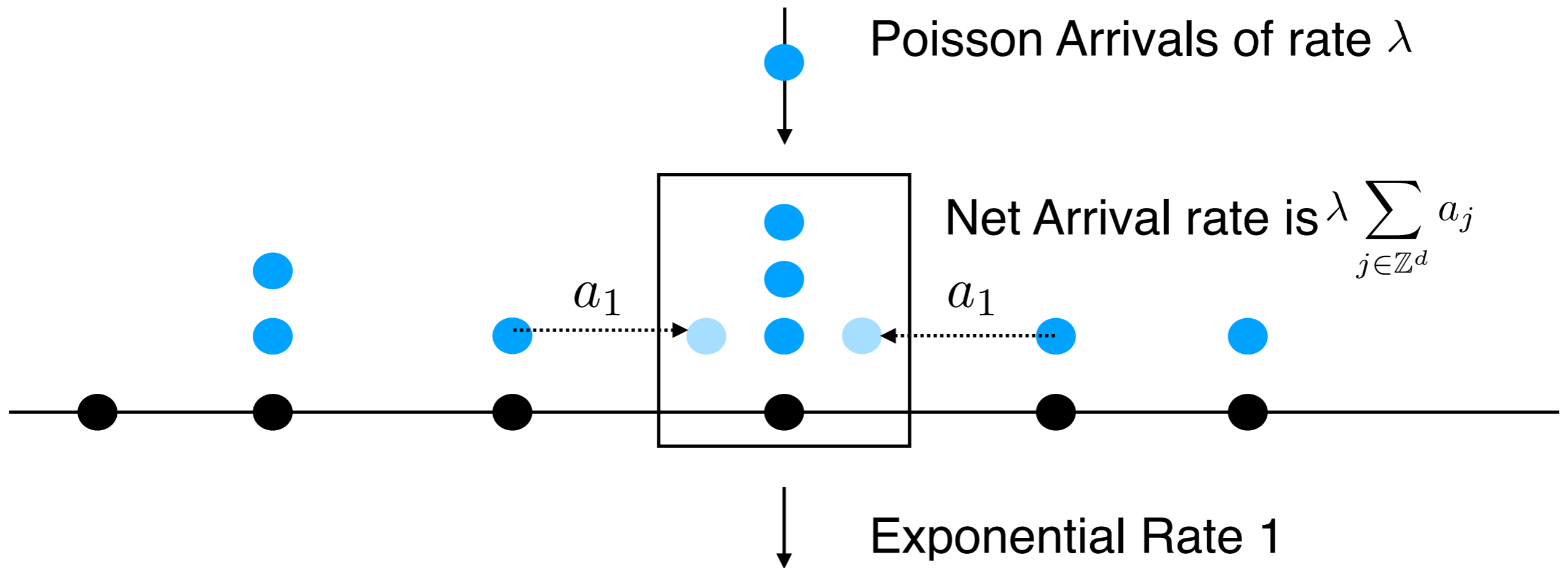
if  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1$ , then this local maximum queue has negative drift



# Intuition



# Intuition



Stability -  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1$

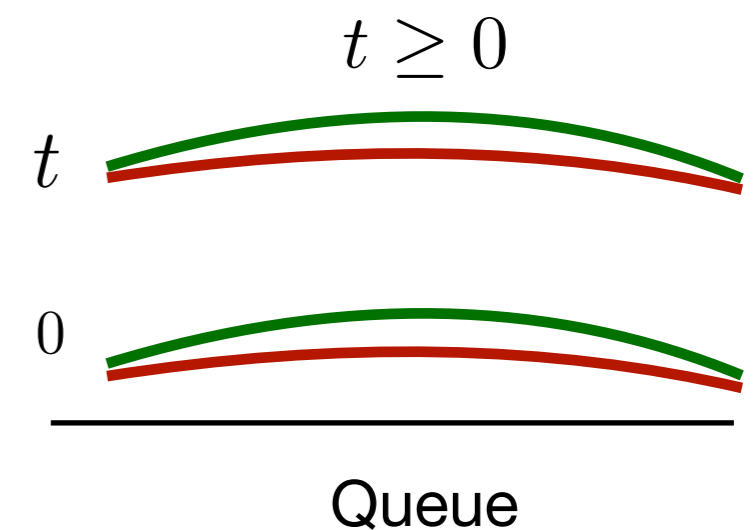
Mean Queue Length -  $\frac{\lambda \sum_{j \in \mathbb{Z}^d} a_j}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j} \cdot \frac{1}{\sum_{j \in \mathbb{Z}^d} a_j}$

*M/M/1*

*Fraction of solid balls*

# Monotonicity

If two initial conditions  $\{x_i(0)\}_{i \in \mathbb{Z}^d}$  and  $\{y_i(0)\}_{i \in \mathbb{Z}^d}$  s.t. for all  $i \in \mathbb{Z}^d$   $x_i(0) \leq y_i(0)$ , then there exists a coupling such that almost-surely  $\forall t \geq 0, \forall i \in \mathbb{Z}^d x_i(t) \leq y_i(t)$ .

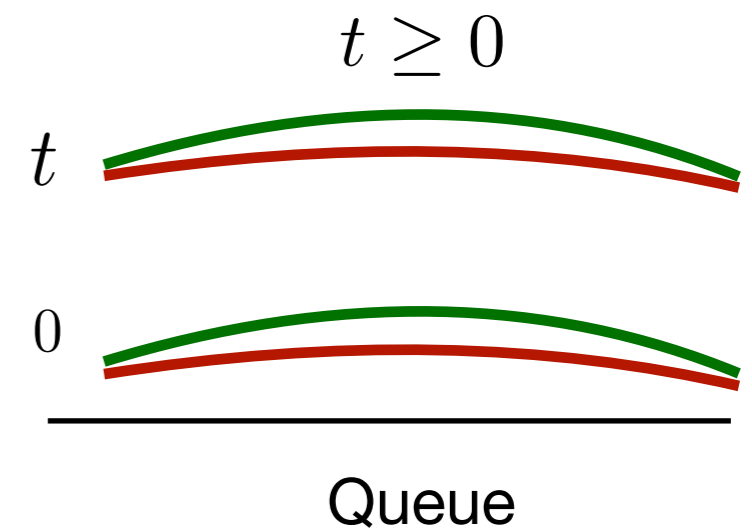


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Proof Induction

Arrivals retain the ordering

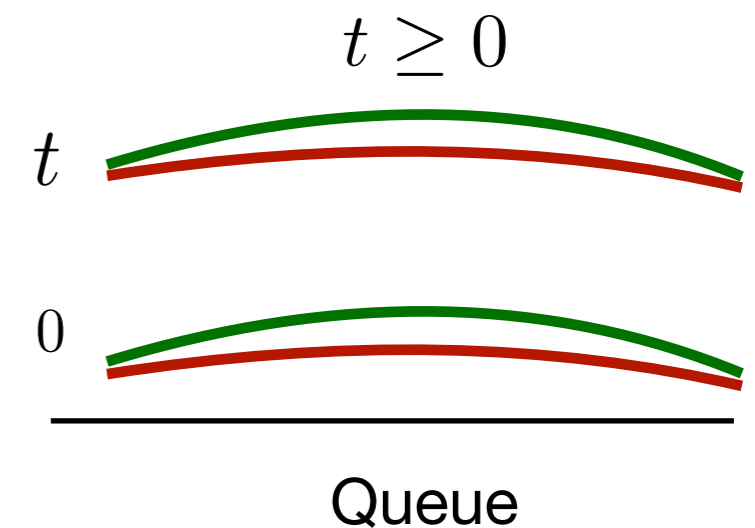


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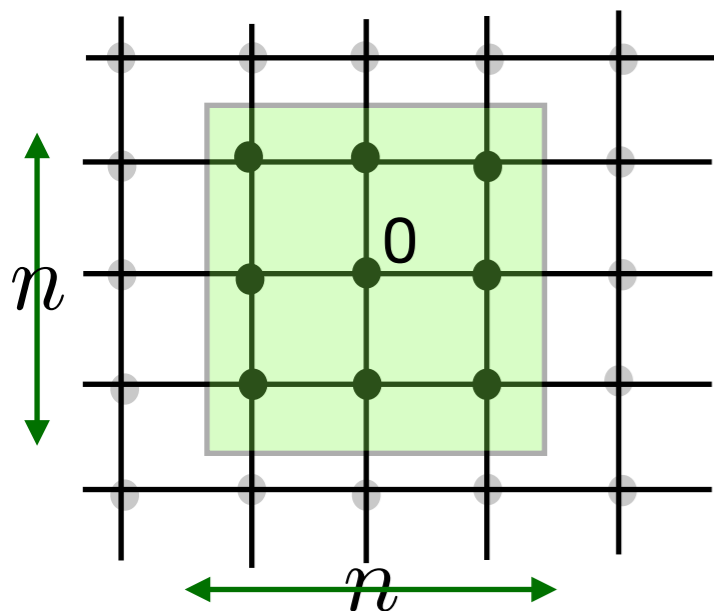
Arrivals retain the ordering



Two queues are equal - higher interference system has smaller departure

Unequal queues - Retains ordering as at-most one customer departs

# Proof Steps



1. Consider a spatial truncation - finite dimensional

2. If  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1 \Rightarrow$  Stability

*Max queue length - Lyapunov function*

3. Rate Conservation Principle

$$\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1 \Rightarrow \mathbb{E}[y_0^{(n)}] = \frac{\lambda}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j} - o_n(1)$$

*Tightness of  $\{y_0^{(n)}\}_{n \in \mathbb{N}}$*

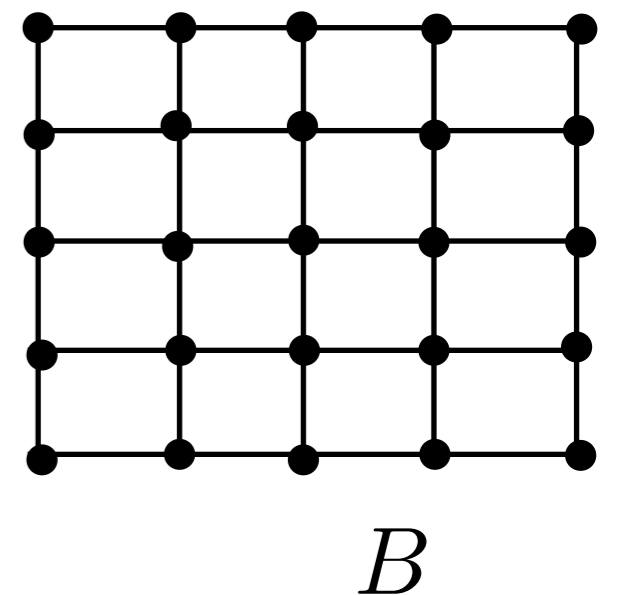
# Main Proof Idea - Stability

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Two systems on  $B \subset \mathbb{Z}^d$  with the same dynamics.  
All queues in  $B^c$  are frozen without activity.

- $\{y_i(t)\}_{i \in B}$  : the set  $B$  is a torus.
- $\{z_i(t)\}_{i \in B}$  : the set  $B$  has boundary effects.

*Interference is lower at the boundaries.*



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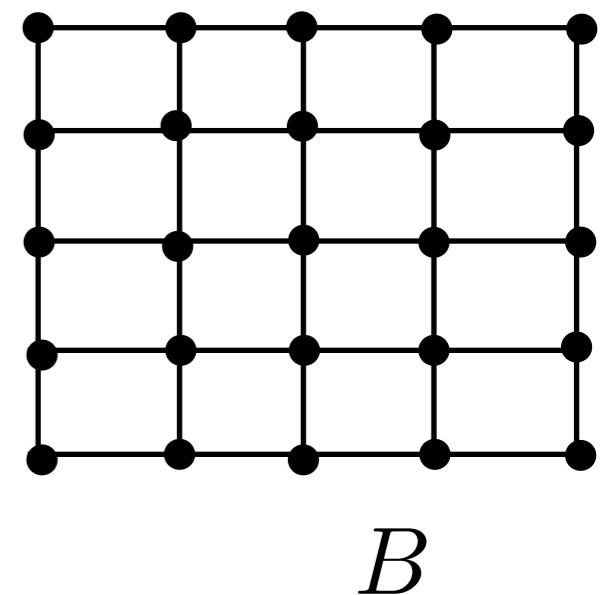
*Interference is lower at the boundaries.*

$$\forall t \forall i \in B$$

$$1) \ x_i(t) \geq z_i(t)$$

$$2) \ y_i(t) \geq z_i(t)$$

*Monotonicity*





# Finite Torus System

---

$\{y_i(t)\}_{i \in B}$  process on a torus.

Theorem - If  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1$ , then  $\{y_i(t)\}_{i \in B}$  is Positive Recurrent and the stationary distribution possess exponential moments. Furthermore, the mean queue length satisfies  $\mathbb{E}[y_0(t)] = \frac{\lambda}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j}$

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## Proof Idea of Stability

$$\frac{d}{dt} y_i = \lambda - \frac{y_i}{\sum_{j \in \mathbb{Z}^d} a_j y_{(i-j)/B}(t)} \quad \text{Fluid scale equation}$$

Consider the maximal queue  $i^*(t) := \arg \max_{i \in B} y_i(t)$

$$\begin{aligned} \frac{d}{dt} y_{i^*(t)} &= \lambda - \frac{y_{i^*(t)}}{\sum_{j \in \mathbb{Z}^d} a_j y_{i^*(t)-j}(t)} \\ &\leq \lambda - \frac{1}{\sum_{j \in \mathbb{Z}^d} a_j} < -\epsilon \end{aligned} \quad \text{This has negative drift}$$

Can upper bound by a stable Single server queue.

# Finite Torus System

---

Rate Conservation - “On Average what comes in is what goes out”.

For Ex. 
$$\lambda = \mathbb{E} \left[ \frac{y_0(t)}{\sum_{j \in \mathbb{Z}^d} a_j y_{j/B}(t)} \mathbf{1}_{y_0(t) > 0} \right]$$

*Avg arrival rate equals avg departure rate.*

Key Idea:

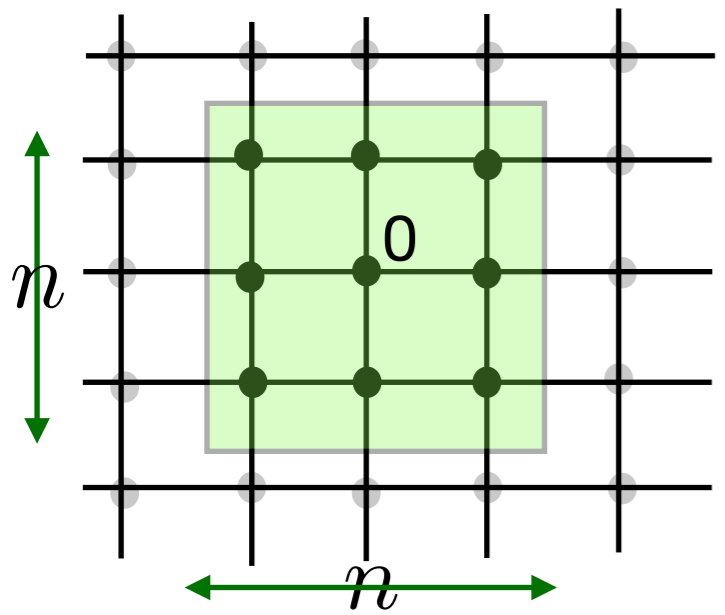
Consider  $I(t) := y_0(t) \sum_{j \in \mathbb{Z}^d} a_j y_j(t)$  in stationarity and solve  $\frac{d}{dt} \mathbb{E}[I(t)] = 0$

Average increase due to arrivals -  $\lambda + \lambda \left( \sum_{j \in \mathbb{Z}^d} a_j \right) \mathbb{E}[y_0(t)]$

Average decrease due to departures -  $\mathbb{E}[y_0(t)]$

Equating the two yields 
$$\mathbb{E}[y_0(t)] \in \left\{ \frac{\lambda}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j}, \infty \right\}$$

# Proof Steps



1. Consider a spatial truncation - finite dimensional

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4. Switch of limits in time and space      *Coupling from the past*

5. Monotone Convergence to yield the moment formula

# Coupling From the Past

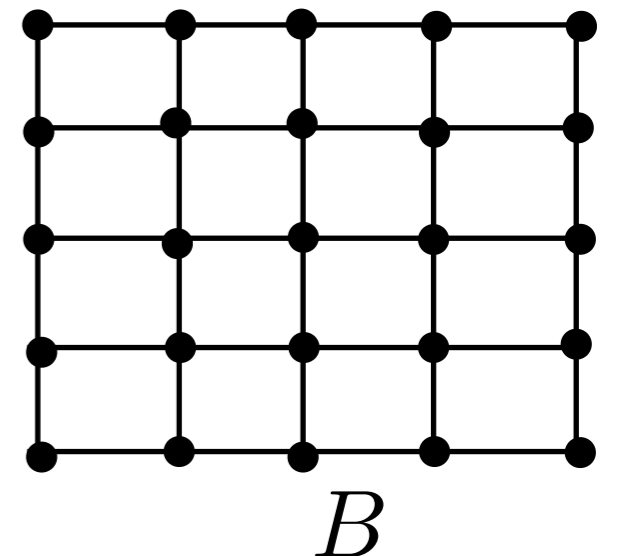
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$\{z_i(t)\}_{i \in B}$ , process where the set  $B$  has boundary effects.

Monotonicity  $\Rightarrow x_i(t) \geq z_i(t)$  and  $y_i(t) \geq z_i(t)$

Thus  $\mathbb{E}[z_0(t)] \leq \frac{\lambda}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j}$  **Uniformly in the size of  $B$**

Consider  $B_n \nearrow \mathbb{Z}^d$  and corresponding stationary  $z_0^{(n)}(0)$



# Coupling From the Past

Let  $B_n \nearrow \mathbb{Z}^d$ .  $z_{0,t}^{(n)}(0)$  - the queue length of queue 0 at time 0, when the truncated  $B_n$  system is started empty at time  $-t$ .

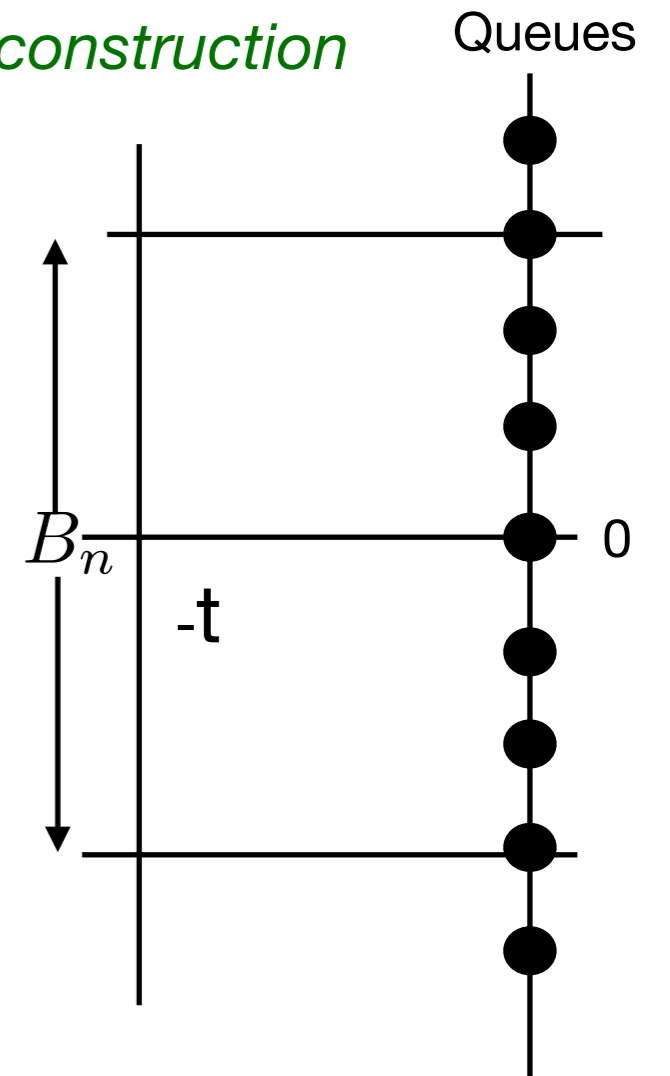
Notice  $\forall t \geq 0 \quad \lim_{n \rightarrow \infty} z_{0,t}^{(n)}(0) = x_{0,t}(0)$  *Corollary of the construction*

Monotonicity  $\Rightarrow$

$$\lim_{t \rightarrow \infty} z_{0,t}^{(n)} := z_{0,\infty}^{(n)} \quad \text{and} \quad \lim_{n \rightarrow \infty} z_{0,\infty}^{(n)} := z_{0,\infty}^{(\infty)} \quad \text{a.s.}$$

We know 
$$\sup_{n \in \mathbb{N}} \mathbb{E}[z_{0,\infty}^{(n)}] \leq \frac{\lambda}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j}$$

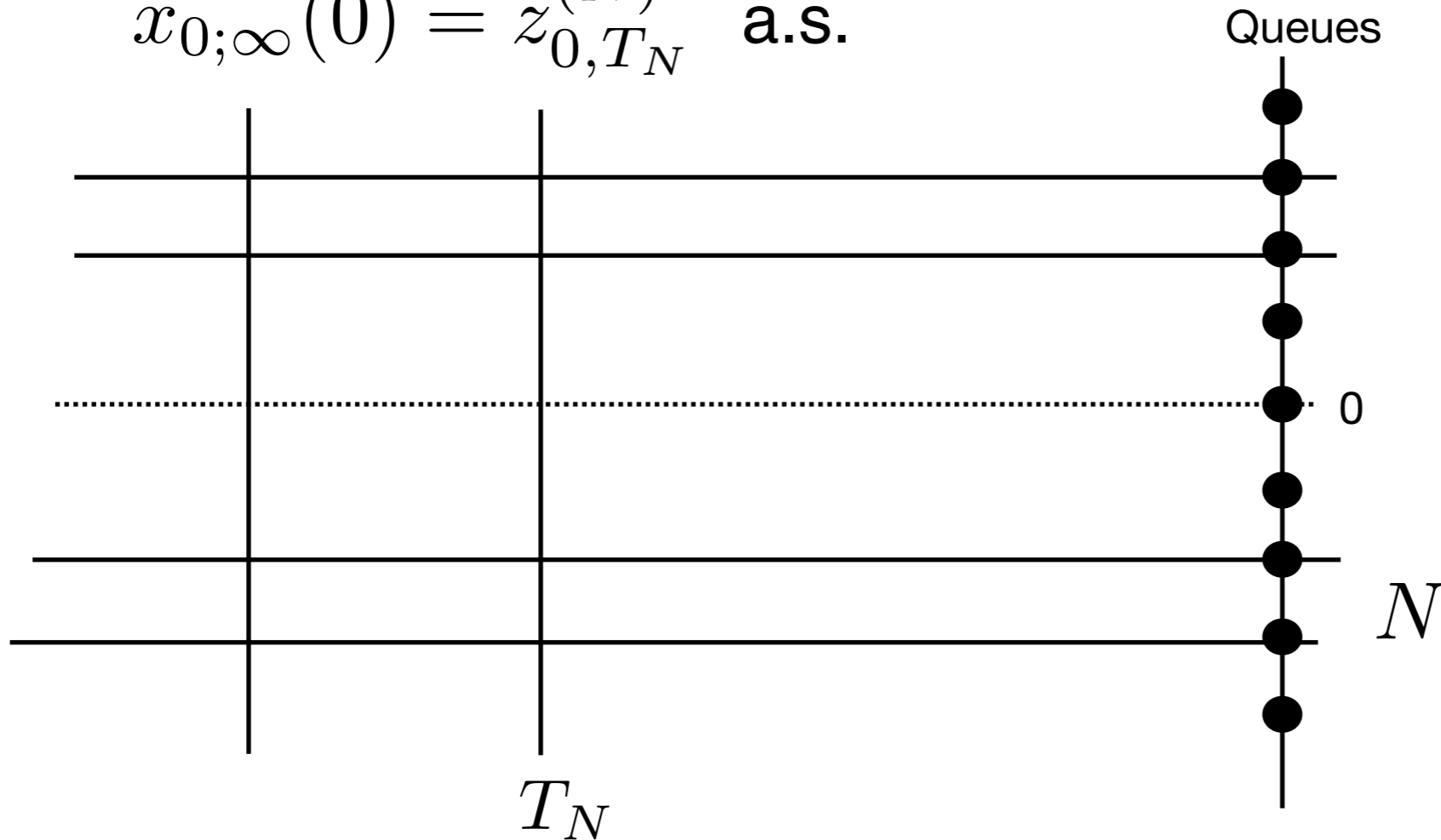
thus, 
$$\mathbb{E}[z_{0,\infty}^{(\infty)}] < \infty$$



# Coupling From the Past

**Lemma** - If  $\lambda \sum_{j \in \mathbb{Z}^d} a_j < 1$ , then  $\exists N \in \mathbb{N}$  and  $\exists T_N < \infty$  random such that

$$x_{0;\infty}(0) = z_{0,T_N}^{(N)} \text{ a.s.}$$



We know  $\sup_{n \in \mathbb{N}} \mathbb{E}[z_{0,\infty}^{(n)}] \leq \frac{\lambda}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j}$ . Thus  $\mathbb{E}[x_{0,\infty}(0)] \leq \frac{\lambda}{1 - \lambda \sum_{j \in \mathbb{Z}^d} a_j}$



# Large Initial Conditions

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## Theorem

For every  $\lambda$ , there exists a probability distribution on  $\mathbb{N}$  such that if the initial condition is  $\{x_i(0)\}_{i \in \mathbb{Z}^d}$  i.i.d. from this distribution, then  $\forall i \in \mathbb{Z}^d$ ,  $\lim_{t \rightarrow \infty} x_i(t) = \infty$  almost-surely.

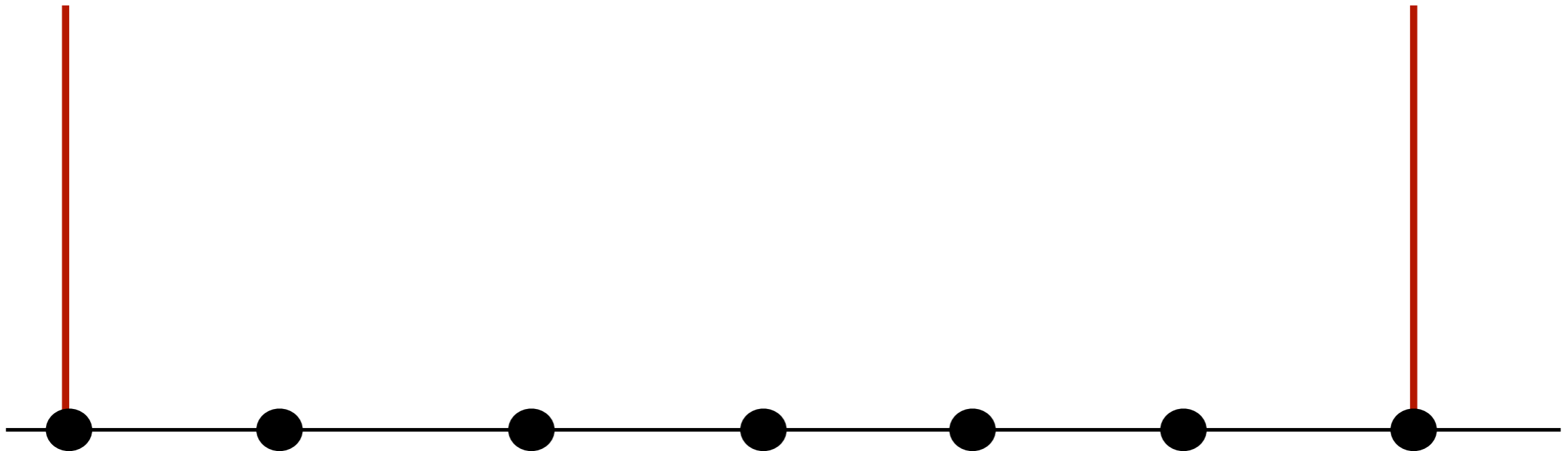


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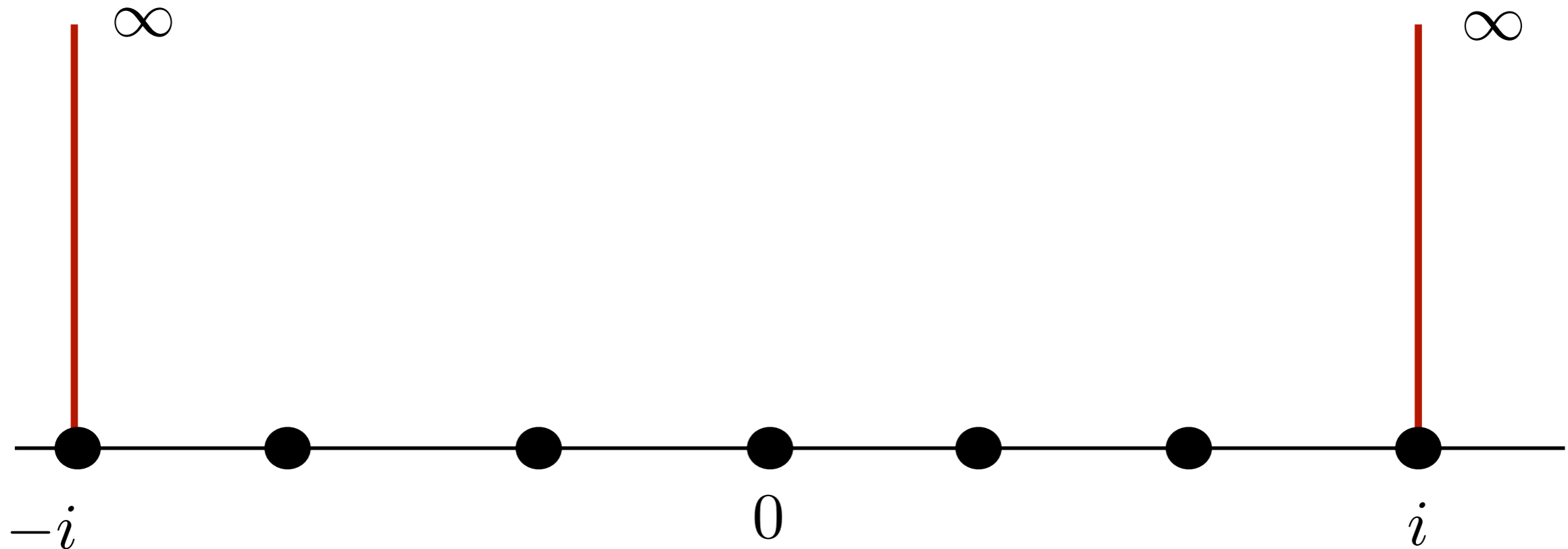
## Theorem

For every  $\lambda$ , there exists a probability distribution on  $\mathbb{N}$  such that if the initial condition is  $\{x_i(0)\}_{i \in \mathbb{Z}^d}$  i.i.d. from this distribution, then  $\forall i \in \mathbb{Z}^d$ ,  $\lim_{t \rightarrow \infty} x_i(t) = \infty$  almost-surely



If “large” frozen boundary is present, then stationary queue length at 0 is also “large” with “high probability”

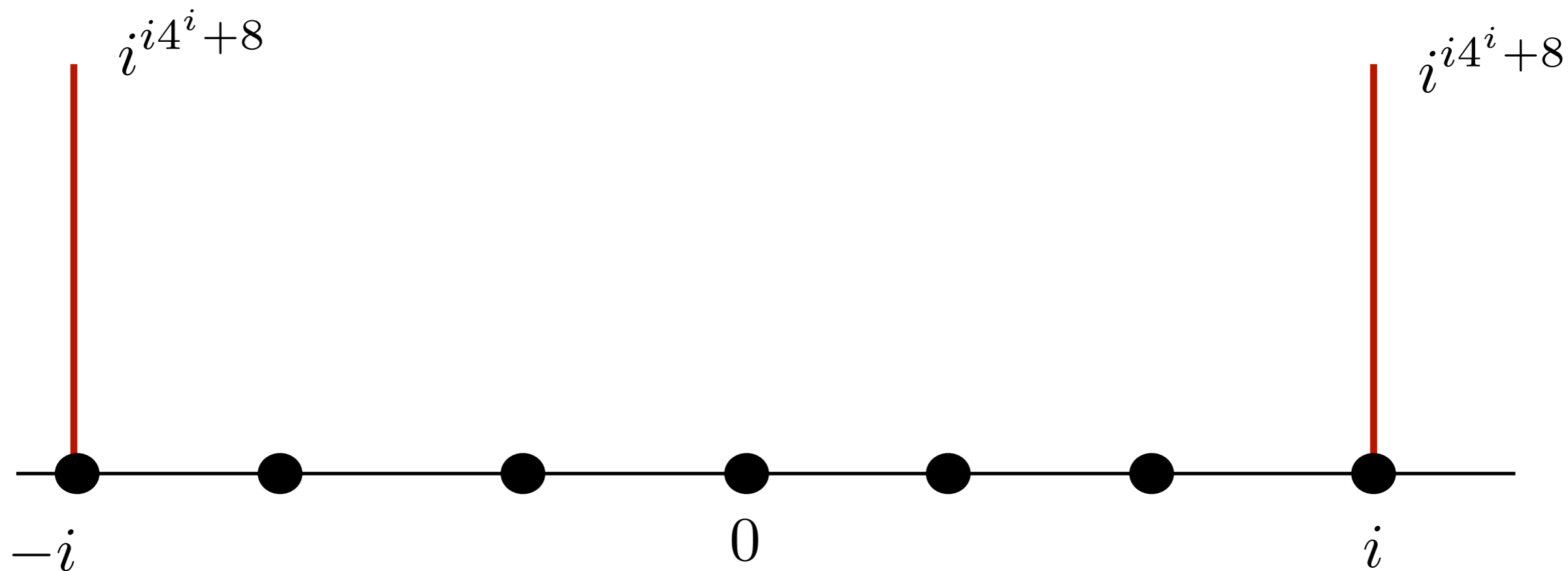
# Convergence to Stationary Solutions



$$\exists (t_i)_{i \in \mathbb{N}} \text{ s.t. } t_i \rightarrow \infty \text{ s.t. } \mathbb{P}[x_0(t_i) < i] \leq i^{-4}$$

Because of the infinite barrier, all queues diverge to infinity at a linear rate

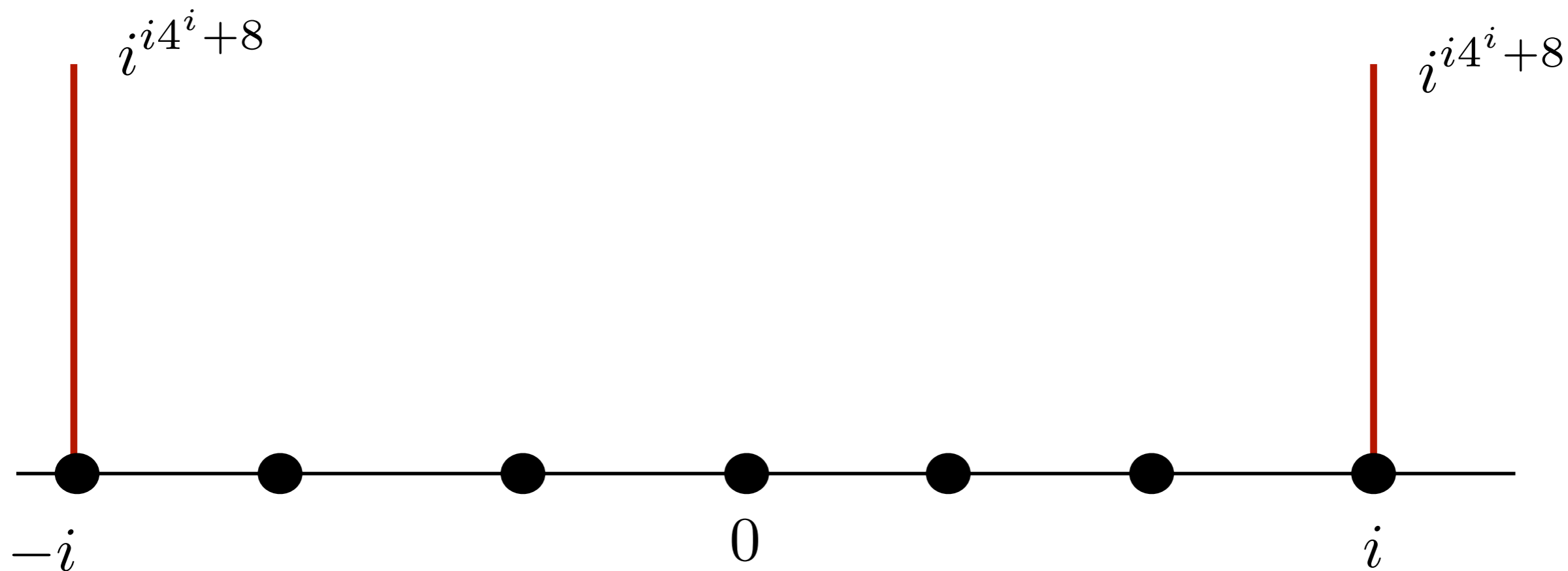
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Since interested only in finite time  $t_i$ , can bring down the barrier to a finite value at a small penalty in probability

# Convergence to Stationary Solutions



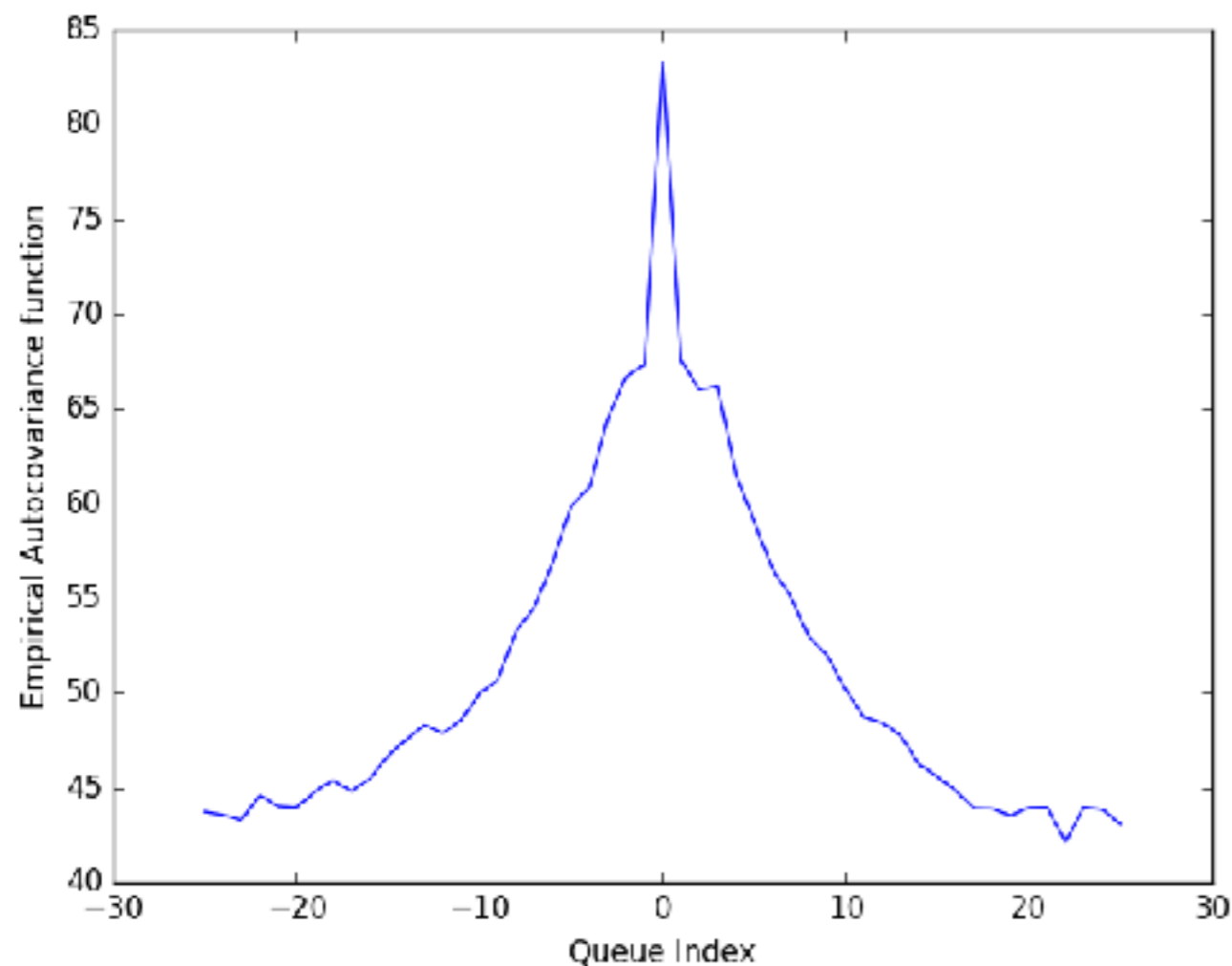
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Since interested only in finite time  $t_i$ , can bring down the barrier to a finite value at a small penalty in probability

Borel-Cantelli to conclude the proof

# Open Questions

How do correlations  $k \rightarrow \mathbb{E}[y_0 y_k] - (\mathbb{E}[y_0])^2$  decay ?



$$d=1, n=51$$

$$\lambda = 0.1419, \lambda_c = 1/7$$

*No propagation of chaos even in an infinite system !*

# Open Questions

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## Uniqueness of Stationary Solution

Existence/construction of other non-degenerate stationary solutions ?

## Convergence to Stationary Solution

Do other initial conditions apart from all empty converge to a stationary limit ?

*Prediction of bad outage events propagating from 'far out' in space*

# Thank You

Related Papers -

- 1) *Interference Queueing Networks on Grids* with F. Baccelli and S. Foss,  
In Annals of Applied Probability, to appear  
<https://arxiv.org/abs/1710.09797>
- 2) *Spatial Birth-Death Wireless Networks*, with F. Baccelli  
In IEEE Transactions on Information Theory, 2017.  
<https://arxiv.org/abs/1604.07884>